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Realizing secret sharing with general access structure

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ABSTRACT

Secret sharing (SS) is one of the most important cryptographic primitives used for data outsourcing. The (t, n) SS was introduced by Shamir and Blakley separately in 1979. The secret sharing policy of the (t, n) threshold SS is far too simple for many applications because it assumes that every shareholder has equal privilege to the secret or every shareholder is equally trusted. Ito et al. introduced the concept of a general secret sharing scheme (GSS). In a GSS, a secret is divided among a set of shareholders in such a way that any "qualified" subset of shareholders can access the secret, but any "unqualified" subset of shareholders cannot access the secret. The secret access structure of GSS is far more flexible than threshold SS. In this paper, we propose an optimized implementation of GSS. Our proposed scheme first uses Boolean logic to derive two important subsets, one is called Min which is the minimal positive access subset and the other is called Max which is the maximal negative access subset, of a given general secret sharing structure. Then, conditions of parameters of a GSS are established based on these two important subsets. Furthermore, integer linear/non-linear programming is used to optimize the size of shares of a GSS. The complexity of linear/non-linear programming is O(n), where n is the number of shares generated by the dealer. This proposed design can be applied to implement GSS based on any classical SS. However, our proposed method is limited to be applicable to some general secret sharing policies. We use two GSSs, one is based on Shamir's weighted SS (WSS) using linear polynomial and the other is based on Asmuth-Bloom's SS using Chinese Remainder Theorem (CRT), to demonstrate our design. In comparing with existing GSSs, our proposed scheme is more efficient and can be applied to all classical SSs.

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1. Introduction

The(t, n) SS was introduced by Shamir [24] and Blakley [2] independently in 1979 and then became one of the most important cryptographic primitives discussed by many researchers [10,17,18,22]. In a (t, n) SS, a dealer divides a secret s into n shares and s is shared among a set of n shareholders, $U = \{U_1, U_2, ..., U_n\}$, in such a way that any t or more than t shareholders can reconstruct the secret s; while fewer than t shareholders cannot reconstruct the secret s. In Shamir's (t, n)

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SS, a dealer generates *n* shares based on a linear polynomial having degreet -1. Secret reconstruction is based on Lagrange interpolating formula using any *t* or more than *t* private shares. Shamir's (t, n) SS is unconditionally secure. There are other types of SSs. For example, Blakely's scheme [2] is based on Geometry, Mignotte's scheme [19] and Asmuth-Bloom's scheme [1] are based on Chinese remainder theorem (CRT), and McEliece et al. scheme [20] is based on Reed-Solomon codes.

The weighted (t, n) secret sharing scheme (WSS) was originally proposed by Shamir [24]. In a WSS, each share of a shareholder has a positive weight. The secret can be recovered if the overall weight of shares is equal to or larger than the threshold; but the secret cannot be recovered if the overall weight of shares is smaller than the threshold value. In fact, Shamir's (t, n) SS is a special type of WSSs in which the weight of all shares is the same. One simple way to implement a WSS using Shamir's (t, n) SS is to assign multiple shares to each shareholder according to his/her weight. There are some papers to discuss properties and characteristics of a WSS. For example, Morillo et al. [21] discussed the property of information rate of a WSS. Beimel et al. [3] characterized all weighted threshold access structures that are ideal. They showed that a weighted threshold access structure is ideal if and only if it is a hierarchical threshold access structure, or a tripartite access structure, or a composition of two ideal weighted threshold access structures that are defined on smaller sets of users.

The secret sharing policy of the (t, n) threshold SS is far too simple for many applications because it assumes that every shareholder has equal privilege to the secret. Complicated sharing policies, in which shareholders have different privileges, can also be realized by other general SSs [4,11]. Ito et al. [11] have introduced the concept of general secret sharing (GSS). In a GSS, a secret is divided among a set of shareholders, U, in such a way that any "qualified" subset of Ucan access the secret, but any "ungualified" subset of Ucannot access the secret. Benaloh et al. [4] have shown that there is a correspondence between the set of general secret sharing functions and the set of monotone functions. Ito et al. [12] have introduced the cumulative array technique and used it to construct a GSS based on monotone access structures. In their scheme, multiple shares are needed for each shareholder. Benaloh et al. [4] have represented the access instances using formulae. According to monotone access instances of a secret, a set of formulae on a set of variables is used to share the secret. Their scheme shares the same problem as scheme proposed by Ito et al. That is, multiple shares are needed for each shareholder. Harn et al. [8] have proposed an *l*-span generalized SS in which the shares can be repeatedly used for r times to reconstruct r different secrets. However, the security of their scheme is based on RSA assumption. Horng [9] propose a method for constructing multiple assignment schemes which is a combination of the threshold scheme and the cumulative scheme. The *cumulative map* is a simple realization of the multiple assignment map based on a (t, n) SS [11] which utilized a GSS based on a WSS. However, the GSSs constructed by the cumulative map are inefficient, Iwamoto et al. [13] proposed an optimal multiple assignments based on integer programming to optimize the size of shares. The complexity of solving an integer programming problem is related to the cardinality of the constraint variables set. However, the number of variables in the integer programming is $O(2^n)$, where n is the number of shares generated by the dealer. Li et al. [15] proposed a method to reduce the number of constraint variables in the integer programming problem. Srinathan et al. [25] have considered the problem of non-perfect secret sharing (NSS) over general secret sharing policy and defined generalized monotone span programs (MSP) to facilitate the design of NSS schemes. However, their approach captures and addresses only NSS schemes that are linear. In 2007, Xu et al. [28] have studied new operations on secret sharing policy to construct large MSPs from small MSPs and proposed new design of GSS. Recently, Guo et al. [6] have proposed a scheme based on the key-lock-pair mechanism. The share of each shareholder is a pair of column vectors corresponding to the key-lock-pair. However, the number of elements of column vectors is determined by the number of terms in the secret access structure. Iftene [14] has proposed a GSS using CRT for special types of general access structures such as the compartmented and the weighted threshold SSs. In 2015, Li et al. [16] have proposed a type of secret sharing schemes called ramp assignment schemes (RAS's) to realize general access structures (AS's). In such a scheme, each participant is assigned a subset of primitive shares of an optimal (k, L, m)-ramp scheme in such a way that the number of primitive shares assigned to each qualified subset is not less than k whereas the one corresponding to any forbidden subset is not greater than k-L. RAS's can be viewed as a generalization of multiple assignment schemes. Very recently, Tochikubo [26] proposed a perfect GSS which is more efficient than schemes based on scheme proposed by Benaloh et al. [4] and Tochikubo [27].

In a GSS, there are two most important subsets, one is called *Min* which is the *minimal positive access subset* and the other is called *Max* which is the *maximal negative access subset*, which characterize any given general secret sharing structure. In this paper, we first uses Boolean logic to derive these two important subsets. Our proposed method is very simple and straightforward. Then, we propose to use these two subsets to implement a GSS. In particular, integer linear/non-linear programming is used to optimize the size of shares of a GSS. Our design is completely different from all existing schemes. This proposed design can be applied to implement GSS based on any classical SS. We use two GSSs, one is based on Shamir's weighted SS (WSS) using linear polynomial and the other is based on Asmuth-Bloom's SS using Chinese Remainder Theorem (CRT), to demonstrate our design. In comparing with existing GSSs, our proposed scheme is more efficient and can be applied to all classical SSs. Here, we summarize the contributions of our paper.

- We propose an optimized design to implement a GSS based on any classical SS.
- For any given general secret sharing policy, Boolean logic is used to derive *Min* and *Max*, then parameters of a GSS are determined based on *Min* and *Max*.
- Integer linear/non-linear programming can be used to minimize the size of shares. The complexity in the integer/non-linear programming is O(n).

- Two GSSs, one is polynomial-based Shamir's WSS and the other is CRT-based Asmuth-Bloom's SS, are used to demonstrate our design.
- Our design can be generalized to implement a GSS based on any classical SS.

The rest of this paper is organized as follows. In the next section, we introduce some preliminaries including CRT, and Asmuth-Bloom SSs based on CRT. In Section 3, we introduce our design to implement a GSS. In Section 4, we demonstrate the optimized implementation of a GSS based on Shamir's WSS using linear polynomial. In Section 5, we demonstrate the optimized implementation of a GSS based on Asmuth-Bloom's SS using CRT. Conclusion is given in Section 6.

2. Preliminaries

In this section, we introduce some preliminaries including CRT, Mignotte's and Asmuth-Bloom schemes based on CRT.

2.1. Chinese remainder theorem (CRT) [5]

Given following system of equations as

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x = s_1 \mod p_1;

x = s_2 \mod p_2;

x = s_t \mod p_t.
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there is one unique solution as $x = \sum_{i=1}^{t} \frac{N}{p_i} \cdot y_i \cdot s_i \mod N$, where $\frac{N}{p_i} \cdot y_i \mod p_i = 1$, and $N = p_1 \cdot p_2 \cdot ... \cdot p_t$, if all moduli are pairwise coprime (i.e., $gcd(p_i, p_i) = 1$, for every $i \neq j$).

CRT has been used in RSA decryption to speed-up the decryption process. With the knowledge of prime decomposition of RSA composite integer and using CRT, the complexity of RSA decryption is reduced by a factor of $\frac{1}{4}$. CRT can also be used in the SS. Each of the shares is represented in a congruence, and the solution of the system of congruences using CRT is the secret to be recovered. SS based on CRT uses, along with CRT, a special sequence of integers that guarantee the impossibility of recovering the secret from a set of shares with less than a certain cardinality. In the next subsections, we will review two most well-known SSs based on CRT.

2.2. Review of Asmuth-Bloom (t, n) SS [1]

Share generation: In Asmuth-Bloom (t, n) SS, the dealer selects p_0 and a sequence of pairwise coprime positive integers, $p_1 < p_2 < ... < p_n$, such that $p_0 \cdot p_{n-t+2} \cdot ... \cdot p_n < p_1 \cdot p_2 \cdot ... \cdot p_t$, and $gcd(p_0, p_i) = 1, i = 1, 2, ..., n$, where p_i is the public information associated with each shareholder, U_i . For this given sequence, the dealer chooses the secret *s* as an integer in the set Z_{p_0} . The dealer selects an integer, α , such that $s + \alpha p_0 \in Z_{p_{n-t+2}:p_{n-t+3}:...:p_n,p_1:p_2....p_t}$. We want to point out that the value, $s + \alpha p_0$, needs to be in the secure secret range, $Z_{p_{n-t+2}:p_{n-t+3}:...:p_n,p_1:p_2....p_t}$; otherwise, the value, $s + \alpha p_0$, can be obtained with fewer than *t* shares. However, in the original paper [1], it specifies that the value, $s + \alpha p_0$, is in the set, $Z_{p_1:p_2....p_t}$. This range is different from the secure secret range. In other words, if $s + \alpha p_0$ is selected to be smaller than the lower bound of the secure secret range (i.e., but it is still in the range, $Z_{p_1:p_2....p_t}$), then the value, $s + \alpha p_0$, can be obtained with fewer than *t* shares. It is obvious that this situation violates one of the security requirements of the (t, n) SS.

Share for the shareholder, U_i , is generated as $s_i = s + \alpha p_0 \mod p_i$, and s_i is sent to shareholder, U_i , secretly, for i = 1, 2, ..., n.

Secret reconstruction: Given a subset of t distinct shares, for example, $\{s_{i_1}, s_{i_2}, ..., s_{i_t}\}$, the secret s can be reconstructed by solving the following system of equations as

 $x = s_{i_1} \mod p_{i_1};$ $x = s_{i_2} \mod p_{i_2};$ \vdots $x = s_{i_t} \mod p_{i_t}.$

Using standard CRT, a unique solution x is given as $x = \sum_{r=1}^{t} \frac{N}{p_{i_r}} \cdot y_{i_r} \cdot s_{i_r} \mod N$, where $N = p_{i_1} \cdot p_{i_2} \cdot \ldots \cdot p_{i_t}$, and $\frac{N}{p_{i_r}} \cdot y_{i_r} \mod p_{i_r} = 1$. Then, the secret s can be recovered by computing $s = x \mod p_0$.

As much and Bloom showed that the entropy of the secret decreases "not too much" when t - 1 shares are known. Interest readers can refer to the original paper [1] for detailed discussion. As much-Bloom's SS can be generalized to take more than t shares in the secret reconstruction. For example, when there are j (i.e., $t < j \le n$) shareholders with their shares, $\{s_1, s_2, ..., s_j\}$, participated in the secret reconstruction, the secret, s_i can be reconstructed using standard CRT to find a unique solution x for the system of j equations.

3. Proposed scheme

In the following, we give a definition of GSS.

Definition 1 (General secret sharing (GSS)). A secret, *s*, is shared according to a given secret sharing policy by a group of *n* shareholders $U = \{U_1, U_2, ..., U_n\}$. A GSS is a method of breaking the secret, *s*, into *n* shares, $s_1, s_2, ..., s_n$, with s_i secretly distributed to U_i such that

- (1) if $A \subseteq U$ is a qualified subset of shareholders, called positive access instance, according to the secret sharing policy, then the secret, *s*, can be reconstructed from shares, $\{s_i | u_i \in A\}$.
- (2) if $A \subseteq U$ is not a qualified subset of shareholders, called negative access instance, according to the secret sharing policy, then the secret, *s*, cannot be reconstructed from shares, $\{s_i | u_i \in A\}$.

The set *F* of all positive access instances is called *positive access structure* of the secret sharing policy and the set *N* of all negative access instances is called *negative access structure* of the secret sharing policy. Suppose the positive access structure of a given sharing policy is *F*. The corresponding negative access structure is *N* with $N \cup F = 2^U$ and $N \cap F = \phi$, where 2^U is the power set of the shareholder set $U = \{U_1, U_2, ..., U_n\}$, the symbol " \cap " is logic AND, and the symbol " \cup " is logic OR.

The positive access structure of a GSS has the monotone increasing property. That is, if $B \in F$, and $B \subseteq C \in U$, then $C \in F$. Similarly, the negative access structure which is the logically complement of the positive access structure of a GSS has the monotone decreasing property. That is, if $B \in N$, and $C \subseteq B \subseteq U$, then $C \in N$.

Definition 2 (Minimal positive access subset and maximal negative access subset). A secret is shared by a set of shareholders according to a given secret sharing policy, where F is the positive access structure and N is the negative access structure, such that

- (1) the subset, $Min \in F$, is the minimal positive access subset if for every $C \subseteq Min$ but $C \{U_i | U_i \in C\} \notin F$; and
- (2) the subset, $Max \in N$, is the maximal negative access subset if for every $C \subseteq Max$ but $C \cup \{U_i | U_i \in U C\} \notin N$.

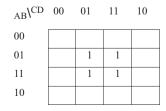
Both *Min* and *Max* can be used to characterize the secret sharing policy completely. For a GSS, if the secret can be recovered by shareholders specified in *Min*, the secret can be recovered by any positive access instance. Similarly, if the secret cannot be recovered by shareholders specified in *Miax*, the secret cannot be recovered by any negative access instance. One contribution of our proposed scheme is to determine both *Min* and *Max* of a general secret sharing policy using Boolean algebra.

3.1. Determining elements in Min and Max using Boolean algebra

Note that the positive access structure of a GSS has the monotone increasing property and the negative access structure has the monotone decreasing property. For example, assume that there are four shareholders, $U = \{A, B, C, D\}$. and a given positive access $A \cap B$. This positive access implies that $\{(A \cap B \cap C \cap D), (A \cap B \cap C' \cap D'), (A \cap B \cap C \cap D), (A \cap B \cap C \cap D')\}$ are positive access instances. For a given negative access $A \cap B$, this negative access implies that $\{(A \cap B \cap C \cap D), (A \cap B \cap C' \cap D'), (A \cap B \cap C \cap D')\}$ are negative access instances. Thus, in a given positive/negative access instances, we first need to simplify these access instances to find a simple representation of positive/negative access.

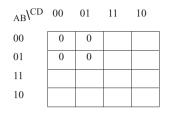
From now on, we use the symbol "F" to represent a positive access structure and the symbol "f" to represent a Boolean function. In the following discussion, we use the Karnaugh map to demonstrate the relation between the access structure and the Boolean function. In the Karnaugh map, each cell is marked by either "1" or "0" to represent its logic value (i.e., "1" stands for "Truth" and "0" stands for "False"). Adjacent 1s in the Karnaugh map represent opportunities to simplify its logic expression. The simplified logic expression can be found by encircling groups of 1s in the map having number of 1s that is a power of two (i.e., 1, 2, 4, 8...). Encircling groups should be as large as possible without containing any 0s. Groups may overlap in order to make each one larger.

If the positive access structure is $F = \{(B \cap D) \cup (B \cap C \cap D) \cup (A \cap B \cap D) \cup (A \cap B \cap C \cap D)\}$, the positive access instances in this access structure can be represented using the Karnaugh map by marking cells with "1s". The Boolean function, $f = (A' \cap B \cap C' \cap D) \cup (A' \cap B \cap C \cap D) \cup (A \cap B \cap C' \cap D) \cup (A \cap B \cap C \cap D) = B \cap D$, corresponds to these "1s" in the Karnaugh map as below.



Thus, in Karnaugh map representation, these four adjacent cells can be grouped together and simplified to be $B \cap D$. Thus, the positive access instances, $\{A' \cap B \cap C' \cap D\}$, $(A' \cap B \cap C \cap D)$, $(A \cap B \cap C \cap D)$, $(A \cap B \cap C \cap D)$, corresponds to $B \cap D$ in the minimal positive subset. In other words, the original access structure $F = \{(B \cap D) \cup (B \cap C \cap D) \cup (A \cap B \cap D) \}$, can be simplified into $F = B \cap D$.

Similarly, if the negative access structure is $N = \{(D) \cup (B \cap D)\}$, the negative access structure can be represented using the Karnaugh map by marking cells with "0s". The Boolean function, $f' = (A' \cap B' \cap C' \cap D') \cup (A' \cap B' \cap C' \cap D) \cup (A' \cap B \cap C' \cap D) \cap (A' \cap B \cap C' \cap D) \cup (A' \cap B \cap C' \cap D) \cup (A'$



Thus, in Karnaugh map representation, these four adjacent cells can be grouped together and simplified to be $A' \cap C'$. Thus, the four negative access instances, $\{(A' \cap B' \cap C' \cap D'), (A' \cap B \cap C' \cap D), (A' \cap B \cap C' \cap D)\}$, corresponds to $B \cap D$ (i.e., $(A \cap B \cap C \cap D) \cap (A' \cap C')$) in the maximal negative subset. In other words, the original negative access structure $N = \{(D) \cup (B \cap D)\}$ can be simplified into $N = B \cap D$.

3.2. Deriving Min and Max from a general secret sharing policy

We use examples to demonstrate our scheme.

Example 1. Assume that there are four shareholders, $U = \{A, B, C, D\}$, and the secret sharing policy can be expressed by the following positive access structure, $F = \{(A \cap B \cap C) \cup (A \cap B \cap D) \cup (B \cap C \cap D) \cup (A \cap C \cap D) \cup (A \cap B \cap C \cap D)\}$. The Boolean functions, $f = (A \cap B \cap C) \cup (A \cap B \cap D) \cup (A \cap B \cap D) \cup (A \cap B \cap C) \cup (A \cap B \cap C)\}$ and $f' = (A' \cap B') \cup (A' \cap C') \cup (A' \cap C') \cup (B' \cap C') \cup (B' \cap D') \cup (C' \cap D')$, correspond to the positive access structure and negative access structure, respectively. The Karnaugh map corresponding to this positive access structure and negative access structure is given below.

$_{AB}$ \ ^{CD}	00	01	11	10
00	0	0	0	0
01	0	0	1	0
11	0	1	1	1
10	0	0	1	0

Karnaugh map simplification is used to derive $Min = \{(A \cap B \cap C) \cup (A \cap B \cap D) \cup (B \cap C \cap D) \cup (A \cap C \cap D)\}$ and $Max = \{(C \cap D) \cup (B \cap C) \cup (A \cap D) \cup (A \cap C) \cup (A \cap C) \cup (A \cap C)\}$.

In this example assume that each shareholder has the same weight. Since $Min = \{(A \cap B \cap C) \cup (A \cap B \cap D) \cup (B \cap C \cap D) \cup (A \cap C \cap D)\}$, it specifies that any 3 or more than 3 shareholders can recover the secret. Furthermore, since $Max = \{(C \cap D) \cup (B \cap C) \cup (A \cap D) \cup (A \cap D) \cup (A \cap C) \cup (A \cap B)\}$, it specifies that any 2 or fewer than 2 shareholders cannot recover the secret. In other words, the secret sharing policy of this example is a (3, 4) SS. This example demonstrates that our proposed scheme can be used to derive both *Min* and *Max* of a threshold secret sharing scheme.

Example 2. Assume that there are four shareholders, $U = \{A, B, C, D\}$, and the secret sharing policy can be expressed by the following positive access structure, $F = \{(A \cap B) \cup (A \cap B \cap C) \cup (B \cap C) \cup (B \cap C \cap D) \cup (A \cap C \cap D) \cup (A \cap B \cap C \cap D)\}$. The Boolean functions, $f = (A \cap B) \cup (A \cap B \cap C) \cup (B \cap C \cap D) \cup (A \cap C \cap D) \cup (A \cap B \cap C \cap D)$ and $f' = (B' \cap C') \cup (B' \cap C) \cup (A' \cap B') \cup (A' \cap C')$, correspond to the positive access structure and negative access structure, respectively. The

Karnaugh map corresponding to this positive access structure and negative access structure is given below.

${}_{AB}\backslash^{CD}$	00	01	11	10
00	0	0	0	0
01	0	0	1	1
11	1	1	1	1
10	0	0	1	0

Karnaugh map simplification is used to derive $Min = \{(A \cap B) \cup (B \cap C) \cup (A \cap C \cap D)\}$ and $Max = \{(A \cap C) \cup (A \cap D) \cup (B \cap D) \cup (C \cap D)\}$. In Sections 4 and 5, *Min* and *Max* of this example will be used to determine optimal size of shares of a GSS.

3.3. Establishing conditions of parameters

The outline of our proposed design is to use both *Min* and *Max* of a given secret sharing policy to determine the parameters of a GSS. Since in a secret sharing policy, *Min* includes all minimal positive access instances and *Max* includes all negative access instances, parameters satisfying *Min* ensure all positive access instances in *F*to recover the secret and parameters satisfying *Max* ensure all negative access instances in *N*not to recover the secret. In other words, our proposed scheme greatly simplifies the implementation of a GSS by only considering parameters satisfying both *Min* and *Max*. The secret of a general secret sharing policy needs to be recovered by the shareholders specified in *Min* and not to be recovered by shareholders specified in *Max*. Conditions of parameters of a GSS satisfying both *Min* and *Max* are established and solved which can enforce the secret sharing policy. In the following, we use examples to demonstrate our scheme.

3.3.1. Implementing a GSS based on Shamir's WSS

Example 3. We want to implement the secret sharing policy in Example 1 based on Shamir's WSS.

We first give the following definition of a weighted (t, n) SS.

Definition 3 (Weighted (t, n) secret sharing scheme (WSS)). A secret, s_i is shared by a group of n shareholders $U = \{U_1, U_2, ..., U_n\}$ having a threshold t. A WSS is a method of breaking the secret, s_i into n shares, $s_1, s_2, ..., s_n$, with s_i secretly distributed to U_i such that

- (1) if $A \subseteq U$ is a qualified subset of shareholders, having the overall weight of shares equal to or larger than the threshold *t*, then the secret, *s*, can be reconstructed from shares.
- (2) if $A \subseteq U$ is not a qualified subset of shareholders, having the overall weight of shares smaller than the threshold t, then the secret, s, cannot be reconstructed from shares.

Shamir's (t, n) SS is a special type of WSSs in which the weight of all shares is the same. One simple way to implement a WSS using Shamir's (t, n) SS is to assign multiple shares to each shareholder according to his/her weight.

In Shamir's WSS, there are different weights of shares. The secret can be recovered if the overall weight of shares is equal to or more than the threshold and the secret cannot be recovered if the overall weight of shares is less than the threshold. Therefore, following parameters of Shamir's WSS need to be determined in order to implement a general secret sharing policy, (a) the threshold of the secret of a WSS, and (b) the weights of shareholders.

Each item in *Min/Maxis* a positive/negative access instance which may involve multiple shareholders. For example, if $U_A \cap U_B$ is a positive access instance in *Min*, it means that U_A and U_B together can recover the secret. To satisfy this requirement, the additive sum of weights of their shares, $w_A + w_B$, needs to be larger than or equal to the threshold, *t*, of the secret. When both U_A and U_B present their shares, the additive sum of weights of their shares, $w_A + w_B$, is larger than or equal to the threshold of the secret so the secret can be recovered from their shares. On the other hand, if $U_C \cap U_D$ is a negative access instance in *Max*, it means that U_C and U_D together cannot recover the secret. To satisfy this requirement, the additive sum of weights of their shares, $w_C + w_D$, needs to be smaller than the threshold of the secret. When both U_C and U_D present their shares, their additive sum, $w_C + w_D$, is smaller than the threshold so the secret cannot be recovered from their shares. If we use min{*Min*} to represent the minimal additive sum of weights in *Min* and max{*Max*} to represent the maximal additive sum of weights in *Max*, the threshold, *t*, of the secret should be selected frommax{*Max*} to represent the maximal additive sum of weights in *Max*, the threshold, *t*, of the secret should be selected frommax{*Max*} to represent the maximal additive sum of weights in *Max*, the threshold, *t*, of the secret should be selected frommax{*Max*} to represent the maximal additive secret sharing policy exactly.

If we assume that the weight of all shares is 1. Then, from Example 1, $Min = \{(A \cap B \cap C) \cup (A \cap B \cap D) \cup (B \cap C \cap D) \cup (A \cap C) \cup (A \cap D)\}$ and $Max = \{(C \cap D) \cup (B \cap D) \cup (B \cap C) \cup (A \cap D) \cup (A \cap C) \cup (A \cap B)\}$. We can obtain $min\{Min\} = 3$ and $max\{Max\} = 2$. Then, from the condition, $max\{Max\} < t \le min\{Min\}$, we have t = 3. In fact, this is a (3, 4) SS in which the threshold is 3 and any 3 or more than 3 shares can recover the secret; but fewer than 3 shares cannot recover the secret. In this example, we demonstrate that both *Min* and *Max* can be used to determine the parameters (i.e., the threshold) of a secret sharing policy (i.e., a threshold SS). In Section 4, we will demonstrate our scheme for a general secret sharing policy.

3.3.2. Implementing a GSS based on Asmuth-Bloom SS

In CRT-based Asmuth-Bloom SS, each shareholder has different modulus. The secret can be recovered if the product of moduli of shareholders is larger than the lower bound of the *secure secret range* and the secret cannot be recovered if the product of moduli of shareholders is smaller than *secure secret range*. Therefore, following parameters of a GSS need to be determined, (a) the *secure secret range*, and (b) the moduli of shareholders.

Each item in *Min/Max*is a positive/negative access instance which may involve multiple shareholders. For example, if $U_A \cap U_B$ is a positive access instance in *Min*, it means that U_A and U_B together can recover the secret. To satisfy this requirement, the shifted value, $s + \alpha p_0$, needs to be smaller than their moduli product, $p_A p_B$. When both U_A and U_B present their shares, their moduli product, $p_A p_B$, is larger than the shifted value so the shifted value can be recovered from their shares. On the other hand, if $U_C \cap U_D$ is a negative access instance in *Max*, it means that U_C and U_B together cannot recover the secret. To satisfy this requirement, the shifted value needs to be larger than their moduli product, $p_C p_D$. When both U_C and U_D present their shares, their moduli product $p_C p_D$ is smaller than the shifted value so the shifter value cannot be recovered from their shares. If we use min{*Min*} to represent the minimal moduli product in *Min* and max{*Max*} to represent the maximal moduli product in *Max*, the shifted value should be selected from max{*Max*} < $s + \alpha p_0 < \min\{Min\}$) in order to satisfy both security requirements. Parameters of a GSS need to be determined to satisfy this inequality relation in order to enforce the secret sharing policy exactly. We use the following example to demonstrate our scheme.

Example 4. We want to implement the secret sharing policy in Example 1 based on Asmuth-Bloom SS.

From Example 1, we have $Min = \{(A \cap B \cap C) \cup (A \cap B \cap D) \cup (B \cap C \cap D) \cup (A \cap C \cap D)\}$ and $Max = \{(C \cap D) \cup (B \cap D) \cup (A \cap D) \cup (A \cap C) \cup (A \cap D)\}$. Recall that the secret sharing policy specified in this example is a (3, 4) SS. Any 3 or more than 3 shareholders can recover the secret, but fewer than 3 shareholders cannot recover the secret s. The moduli products in *Min* of Asmuth-Bloom (3, 4) SS can be represented as $\{p_{r_i} \cdot p_{r_{i+1}}, p_{r_{t+2}} | \forall p_{r_i}, p_{r_{i+1}}, p_{r_{t+2}} \in \{p_A, p_B, p_C, p_D\}\}$ and the moduli products in *Max* can be represented as $\{p_{r_i} p_{r_{i+1}} | \forall p_{r_i}, p_{r_{i+1}} \in \{p_A, p_B, p_C, p_D\}\}$. To satisfy the secret sharing policy, the secure secret range can be specified as $\max\{Max\} < s + \alpha p_0 < \min\{Min\}$. However, if all moduli satisfy $p_A < p_B < p_C < p_D$ such that $p_0 \cdot p_C \cdot p_D < p_A \cdot p_B \cdot p_C$, then we have $\min\{Min\} = p_A \cdot p_B \cdot p_C$ and $\max\{Max\} = p_C \cdot p_D$. Thus, we have $p_C \cdot p_D < s + \alpha p_0 < p_A \cdot p_B \cdot p_C$, which is the secure secret range as we described in Section 2.2.

In this example, we demonstrate that both *Min* and *Max* can be used to determine the parameters (i.e., the *secure secret range*) of a secret sharing policy (i.e., a threshold SS). In Section 5, we will demonstrate our scheme for a general secret sharing policy.

4. Optimized implementation of GSS based on Shamir's WSS

In this section, we show how to use linear integer programming to optimize the size of shares of a GSS.

4.1. Proposed scheme

We illustrate our proposed scheme in Fig. 1. We use the following example to demonstrate our scheme.

Example 5. We want to implement the secret sharing policy in Example 2 based on Shamir's WSS.

From Example 2, we have $Min = \{(A \cap B) \cup (B \cap C) \cup (A \cap C \cap D)\}$ and $Max = \{(A \cap C) \cup (A \cap D) \cup (B \cap D) \cup (C \cap D)\}$. Assume that the weights of shares of shareholders, A, B, C and D are w_A, w_B, w_C, w_D , respectively. If we use min $\{Min\}$ to represent the minimal additive sum of weights in Min and max $\{Max\}$ to represent the maximal additive sum of weights in Min and max $\{Max\}$ to represent the maximal additive sum of weights in Min and max $\{Max\} < t \le \min\{Min\}$. In other words, the upper bound of the threshold is min $\{w_A + w_B, w_B + w_C, w_A + w_C + w_D\}$ and the lower bound of the threshold is max $\{w_A + w_C, w_A + w_C, w_B + w_D, w_C + w_D\}$. Since the additive sum of weights of shareholders of each item in Min should be larger than the additive sum of weights of shareholders of each item in Max, we can establish the following inequality conditions.

From $w_A + w_B > \{w_A + w_C, w_A + w_D, w_B + w_D, w_C + w_D\} \Rightarrow w_B > w_C, w_B > w_D, w_A > w_D$.

From $w_B + w_C > \{w_A + w_C, w_A + w_D, w_B + w_D, w_C + w_D\} \Rightarrow w_B > w_A, w_B + w_C > w_A + w_D, w_C > w_D, w_B > w_D.$

From $w_A + w_C + w_D > \{w_A + w_C, w_A + w_D, w_B + w_D, w_C + w_D\} \Rightarrow w_A + w_C > w_B$.

In summary, we have $w_B > w_C > w_D, w_B > w_A > w_D, w_B + w_C > w_A + w_D, w_A + w_C > w_B$.

Linear integer programming can be used to determine these weights. It is well known that solving linear integer problems belong to the class of NP-hard optimization problems [7]. The complexity of solving an integer programming problem is related to the cardinality of the constraint variables set. The number of variables in the integer programming proposed by Iwamoto et al. [13] is $O(2^n)$, where *n* is the number of shares generated by the dealer; but, in our proposed scheme, the number of variables in liner integer programming is O(n). In most GSSs, since the number of shareholders is limited to be a small integer (say 10), this can greatly simplify the processing time to determine the variables.

The objective function, *O*, in a linear programming can be set up as, $O = \min(\{\max\{w_1, w_2, ..., w_n\})\}$, to minimize the largest weight among all weights of shareholders, or $O = \min(\sum_{i=1}^{n} w_i)$, to minimize the sum of all weights of shareholders. In this given example, if we set $O = \min(w_A + w_B + w_C + w_D)$, we can obtain $w_A = 3$, $w_B = 4$, $w_C = 2$, $w_D = 1$ and t = 6. A Shamir's WSS can be used to implement this GSS by setting the threshold of the secret to be 6 and assigning $w_A = 3$, $w_B = 4$, $w_C = 2$, $w_D = 1$, to shareholders, A, B, C and D, respectively. The dealer follows Shamir's (6, 10) SS to select a polynomial

Parameters generation:

Inputs: s,*n*,*F* = Secret sharing policy,*O* = Objective function.

- 1. For the given positive access structure, *F*, derive the minimal positive access subset, *Min*, and maximal negative access subset, *Max*.
- 2. Establish inequality conditions of weights of shareholders based on relations of additive sums of weights in the subsets, *Min*, and *Max*.
- 3. Solve weights, w_i , for i = 0,1,...,n, using linear optimization with objective function, *O*, and subject to conditions obtained in Step 2, and $max{Max} < t \le min{Min}$.

For example, if we select the objective function is $O = minimize w_A + w_B + w_C + w_D$, then we solve

$$\begin{split} O &= minimize \ w_A + w_B + w_C + w_D \\ s.t. \left\{ \begin{array}{l} w_B > w_C > w_D \\ w_B > w_A > w_D \\ w_B + w_C > w_A + w_D \\ w_A + w_C > w_B \end{array} \right\}. \end{split}$$

Outputs: $t, w_1, ..., w_n$.

Share generation:

Generate shares following Shamir's (t,n) threshold SS. The dealer selects a polynomial with degree t-1 and generates shares for shareholders. Each shareholder has multiple shares according to his/her weight. Each share is sent to shareholder secretly.

Secret reconstruction:

Given any t or more than t distinct shares, the secret can be reconstructed following the classical Shamir's secret reconstruction.

Fig. 1. Proposed GSS based on WSS.

having degree 5 and generates 3 shares for A, 4 shares for B, 2 shares for C and 1 share for D. Secret can be recovered when there are 6 or more than 6 shares available. The secret reconstruction follows classical Shamir's (t, n) SS.

Remark 1. If contradict conditions, such as $w_A > w_B$ and $w_B > w_A$, derived from our scheme, there have no solutions for weights of shareholders. In the following example, we show that such contradict conditions may occur and this proposed scheme cannot be used to provide solution. Conditions in a given position access structure which cannot be implemented by a weighted SS deserve further study.

Example 6. Assume that there are four shareholders, $U = \{A, B, C, D\}$, and the secret sharing policy can be expressed by the following positive access structure, $F = (A \cap B) \cup (C \cap D)$. The Karnaugh map corresponding to this positive access structure and negative access structure is given below.

Karnaugh map simplification is used to derive $Min = \{(A \cap B) \cup (C \cap D)\}$ and $Max = \{(B \cap D) \cup (B \cap C) \cup (A \cap C)\}$. Assume that the weights of shares of shareholders, A, B, C and D are w_A, w_B, w_C, w_D , respectively. If we use min $\{Min\}$ to represent the minimal additive sum of weights in Min and max $\{Max\}$ to represent the maximal additive sum of weights in Max, the threshold, t, of the secret should be selected frommax $\{Max\} < t \le \min\{Min\}$. In other words, the upper bound of the threshold is min $\{w_A + w_B, w_C + w_D\}$ and the lower bound of the threshold is max $\{w_B + w_D, w_B + w_C, w_A + w_C\}$. Since the additive sum of weights of shareholders of each item inMin should be larger than the additive sum of weights of shareholders of each item inMax, we can establish following inequality conditions.

From $w_A + w_B > \{w_B + w_D, w_B + w_C, w_A + w_C\} \Rightarrow w_A > w_D, w_A > w_C, w_B > w_C$. From $w_C + w_D > \{w_B + w_D, w_B + w_C, w_A + w_C\} \Rightarrow w_C > w_B, w_D > w_B, w_D > w_A$. In summary, we have several contradict conditions from these inequality conditions.

4.2. Security analysis

In our proposed GSS, the threshold, t, of the secret is determined from $\max\{Max\} < t \le \min\{Min\}$. For any positive access instance in a minimal positive access subset, the additive sum of weights of this access instance is larger than or equal to the threshold (i.e., $t \le \min\{Min\}$). Thus, the secret can be recovered from shares of any positive access instance in F. On the other hand, for any negative access instance in a maximal negative access subset, the additive sum of weights of this negative access instance is smaller than the threshold (i.e., $t > \max\{Max\}$). Thus, the secret cannot be recovered from shares of any negative access instance in N.

5. Optimized implementation of GSS based on Asmuth-Bloom SS

5.1. Proposed scheme

We illustrate our proposed scheme in Fig. 2. In our proposed CRT-based GSS, the dealer follows the same procedure as Asmuth-Bloom (t, n) SS to select a secret, s, in the set Z_{p_0} . Then, the dealer selects an integer, α , and linearly shifts the secret as $s + \alpha p_0$, into the secure secret range. The share of shareholder, U_i , is computed as $s + \alpha p_0$ mod p_i . In the following, we first explain how to determine the secure secret range of the shifted value, $s + \alpha p_0$, such that it can enforce the secret sharing policy. Then, we will explain how to determine moduli of shareholders.

Let us assume that there are *n* shareholders and each shareholder, U_i , has a public modulus, p_i . For a general secret access structure, following Section 3.2, we can derive *Min* and *Max*. Each item in *Min/Max* is an access instance which involve multiple shareholders. For example, if $U_A \cap U_B$ is one minimal positive instance in *Min*, it means that U_A and U_B together can recover the secret. To satisfy this requirement, the shifted value, $s + \alpha p_0$, needs to be smaller than their moduli product, $p_A p_B$. When both U_A and U_B present their shares, their moduli product, $p_A p_B$, is larger than the shifted value so the shifted value can be recovered from their shares. On the other hand, if $U_C \cap U_D$ is one maximal negative access instance in *Max*, it means that U_C and U_B together cannot recover the secret. To satisfy this requirement, the shifted value enceds to be larger than their moduli product, $p_C p_D$. When both U_C and U_D present their shares, their shares, their moduli product $p_C p_D$ is smaller than the shifted value so the shifted value cannot be recovered from their shares. If we use min{*Min*} to represent the minimal moduli product in *Min* and max{*Max*} to represent the maximal module product in *Max*, the shifted value should be selected from the secure secret range, as (max{*Max*}, min{*Min*}) (*i.e.*, max{*Max*} < $s + \alpha p_0 < \min{Min}$) in order to satisfy both security requirements. We use the following example to demonstrate our design.

Example 7. We want to implement the secret sharing policy in Example 2 based on Asmuth-Bloom (t, n) SS.

From Example 2, we have $Min = \{(A \cap B) \cup (B \cap C) \cup (A \cap C \cap D)\}$ and $Max = \{(A \cap C) \cup (A \cap D) \cup (B \cap D) \cup (C \cap D)\}$. Assume that the moduli of A, B, C and D are p_A, p_B, p_C, p_D , respectively. The upper bound of the secure secret range is $\min\{p_Ap_B, p_Bp_C, p_Ap_Cp_D\}$ and the lower bound of the secure secret range is $\max\{p_Ap_C, p_Ap_D, p_Bp_D, p_Cp_D\}$. Since every moduli product in *SetMax*, we have following inequality conditions.

From $p_A p_B > \{ p_A p_C, p_A p_D, p_B p_D, p_C p_D \} \Rightarrow p_B > p_C, p_B > p_D, p_A > p_D.$

From $p_B p_C > \{p_A p_C, p_A p_D, p_B p_D, p_C p_D\} \Rightarrow p_B > p_A, P_B P_C > P_A P_D, p_C > p_D, p_B > p_D.$

From $p_A p_C p_D > \{p_A p_C, p_A p_D, p_B p_D, p_C p_D\} \Rightarrow p_B > p_C, p_A p_C > p_B$.

In summary, we obtain the following inequality conditions, $p_B > p_C > p_D, p_B > p_A > p_D, p_A p_C > p_B$.

Parameters generation:

Inputs: $s, p_0, n, F =$ Secret sharing policy, O = Objective function.

- 1. For the given positive access structure, *F*, derive the minimal positive access subset, *Min*, and maximal negative access subset, *Max*.
- 2. Establish inequality conditions of moduli of shareholders based on relations of moduli products in the subsets, *Min*, and *Max*.
- 3. Solve moduli, p_i , for i = 0,1,...,n, with $gcd(p_i, p_j) = 1, i \neq j$, using nonlinear optimization with objective function, O, and subject to conditions obtained in Step 2, $max\{p_Ap_C, p_Ap_D, p_Bp_D, p_Cp_D\} < s + \alpha p_0 < min\{p_Ap_B, p_Bp_C, p_Ap_Cp_D\}, p_0 \cdot max\{Max\} < min\{Min\}, and <math>p_0 > s > 0$.

For example, if we select the objective function is $O = \mininize (\{max\{p_A, p_B, p_C, p_D\})\}$, then we solve

$$O = \mininimize \left(\{ max\{p_A, p_B, p_C, p_D \} \} \right)$$
s.t.
$$\begin{cases} max\{p_Ap_C, p_Ap_D, p_Bp_D, p_Cp_D \} < s + \alpha p_0 < \min\{p_Ap_B, p_Bp_C, p_Ap_Cp_D \} \\ p_0 \cdot max\{Max\} < \min\{Min\} \\ p_0 > s > 0 \end{cases}$$

Outputs: p_1, \ldots, p_n .

4. Solve the linearly shifted value, $s' = s + \alpha p_0 \in (max\{Max\}, min\{Min\})$.

Share generation:

Share for the shareholder, U_i , is generated as $s_i = s + ap_0 \mod p_i$. s_i is sent to shareholder, U_i , secretly.

Secret reconstruction:

Given any subset of distinct shareholders satisfying the positive access structure, the secret value, $s'=s+\alpha p_0$, can be reconstructed by using the standard CRT. Then, the secret s can be recovered by computing $s=s' \mod p_0$.

Fig. 2. Proposed GSS based on CRT.

We can use non-linear integer programming to determine these moduli. The objective function, O, can be set up to minimize the size of shares. For example, if $O = \min(\{\max\{p_1, p_2, ..., p_n\})$, it minimizes the largest modulus in all moduli of shareholders, or $O = \min(\sum_{i=1}^{n} p_i)$, it minimizes the sum of moduli of shareholders. The product form of variables can be easily avoided and changes the problem into a linear integer optimization [23]. More research works are needed to solve our proposed non-linear integer programming.

Remark 2. Following the same discussion in Remark 1, the contradict conditions, such as $p_A > p_B$ and $p_B > p_A$, cannot be occurred in our scheme.

5.2. Security

In our proposed GSS, the shifted value, $s + \alpha p_0$, is from the secure secret range i.e., max{Max} < $s + \alpha p_0 < \min{Min}$. For any positive access instance, the moduli product of this access instance is larger than the shifted value (i.e., $> \min{Min}$). Thus, the shifted value can be recovered from shares of this access instance. On the other hand, for any negative access

instance, the moduli product of this negative access instance is smaller than the shifted value (i.e., $< \max\{Max\}$). Thus, the shifted value cannot be recovered from shares of this negative access instance.

Let us analyze the security of a different situation. We assume that $U_A \cap U_B \cap U_C$ is one positive access instance in the minimal positive access subset. Shareholders, U_A and U_B , with their shares together can recover a value, $s'' \in (0, p_A p_B)$. The "real" shifted value, $s' = s + \alpha p_0$, selected in the secure secret range, $\max\{Max\} < s + \alpha p_0 < \min\{Min\}$, is different from $s'' \in (0, p_A p_B)$ since $s'' \in (0, p_A p_B) < \max\{SetMax\}$. Shareholders, U_A and U_B , together cannot recover the "real" shifted value from s''. However, there exists the following relation between s'' and s''. That is, $s''' + \lambda p_0 = s' \in (\max\{Max\}, \min\{Min\})$. The number of possible values of λ which can shift s'' into the secure secret range, $\max\{Max\} < s + \alpha p_0 < \min\{Min\}$, is $\frac{\min\{Min\}-\max\{Max\}}{p_A p_B}$. However, there is only one λ corresponding to the "real" shifted value. Since the modulus, p_0 , satisfies $p_0 \cdot \max\{Max\} < \min\{Max\} < \min\{Min\}$, we have $\frac{\min\{Min\}-\max\{Max\}}{p_A p_B} > \frac{\min\{Min\}-\max\{Max\}}{\max\{Max\}} > \frac{p_0 \cdot \max\{Max\}}{\max\{Max\}} > p_0 - 1$. Thus, the collection of possible values of λ is no less than the collection of possible values of the secret s. No useful information is leaked from the collection of shares in this case.

6. Conclusion

The secret sharing policy of the (t, n) threshold SS is far too simple for many applications because it assumes that every shareholder has equal privilege to the secret. A general design to implement a GSS based on any classical SS is proposed in this paper. The dealer first determines *Min* and *Miax* from a secret sharing policy and then use this information to obtains inequality conditions of parameters of a GSS. Integer optimization is used to minimize the size of shares. Two GSSs, one is based on WSS using linear polynomial and the other is based on Asmuth-Bloom (t, n) SS using CRT, are included to demonstrate our design.

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